



南京航空航天大学

Nanjing University of Aeronautics and Astronautics



模式分析与机器智能
工业和信息化部重点实验室

MIT Key Laboratory of
Pattern Analysis & Machine Intelligence

Open Set Learning with Counterfactual Images

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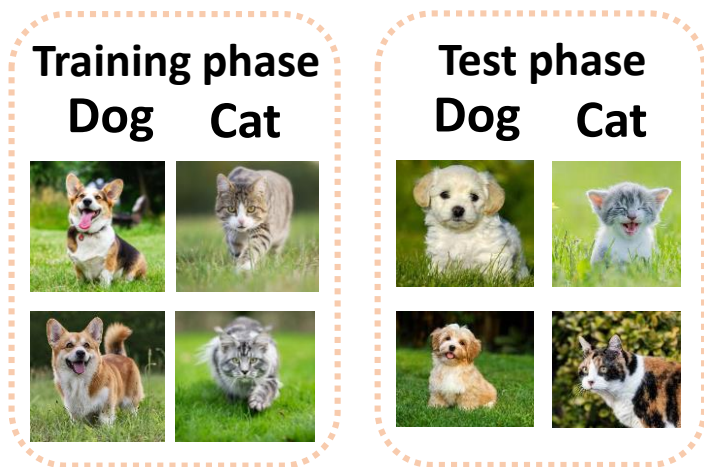
Collaborative Robotics and Intelligent Systems Institute
Oregon State University

ECCV 2018

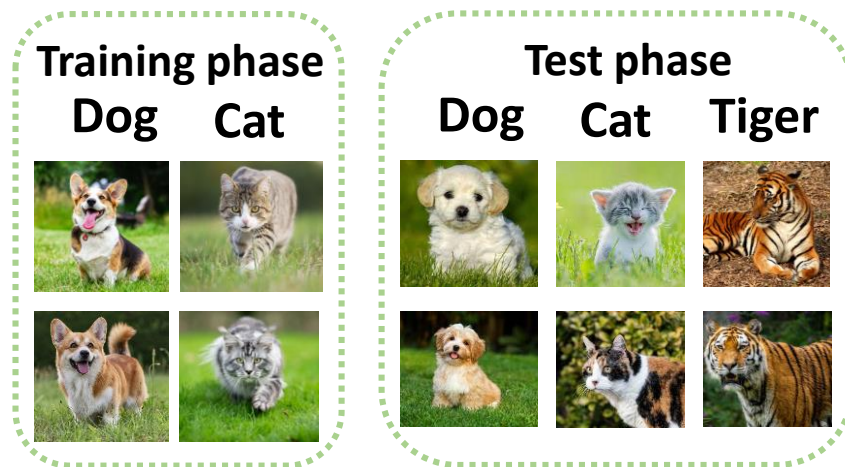
Open Set Recognition



- **Open set classification vs. closed set classification**



Closed set classification



Open set classification

- Thresholding

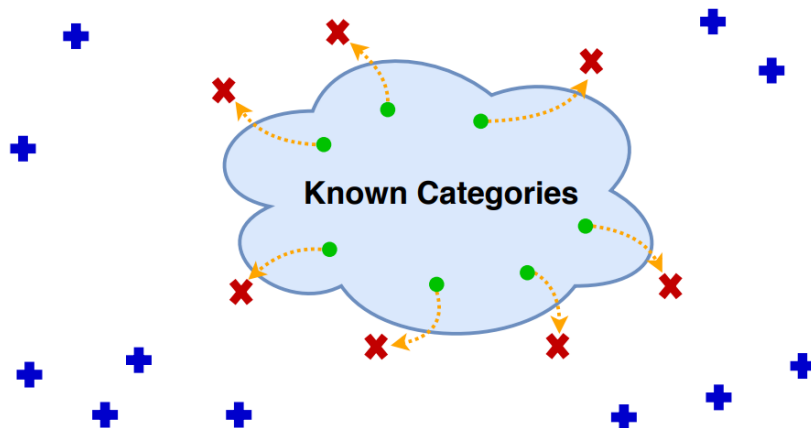
$$y^* = \begin{cases} \arg \max_{y_i} P(y_i|x) & \text{if } \max_{y_i} P(y_i|x) > \delta \\ \textit{unknown} & \text{else} \end{cases}$$

- Potential limitation
 - It is difficult to find the optimal **global** threshold.
 - DNNs can output **incorrect high-confidence predictions** when faced with test data from outside the training distribution.
- OpenMax
 - Using Extreme Value Theory (EVT) to calibrate the model outputs.

Main Idea



- Counterfactual images

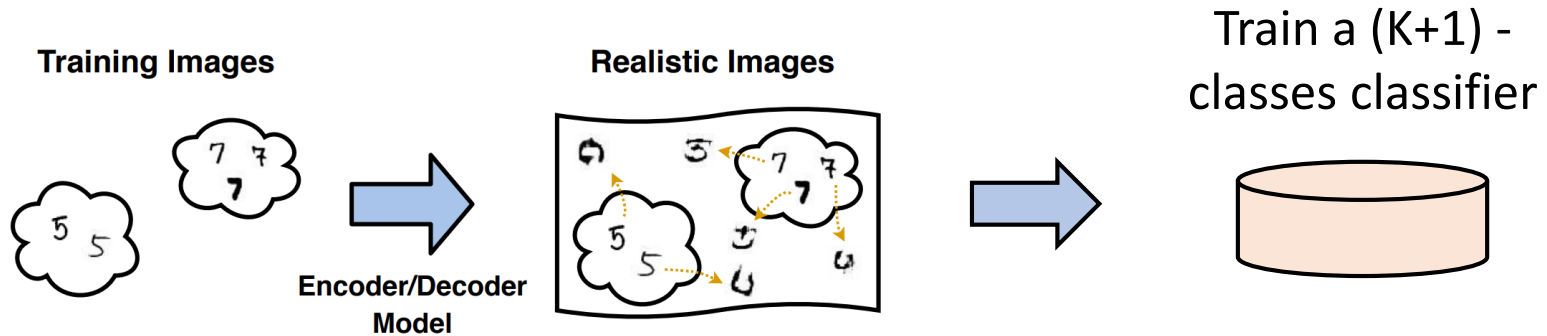


minimize
subject to

$$\|z_0 - z^*\|_2$$
$$C_p(z^*) = 1$$

The Proposed Method

- Overview



- The generative model

$$\mathbf{L}_D = \sum_{x \in \mathbf{X}} D(G(E(x))) - D(x) + P(D)$$

$$\mathbf{L}_G = \sum_{x \in \mathbf{X}} \|x - G(E(x))\|_1 - D(G(E(x)))$$

The Proposed Method



- Generating Counterfactual Open Set Examples

minimize $\|E(x) - z^*\|_2$
subject to $G(z^*)$ is an open set example

$$z^* = \min_z \|z - E(x)\|_2^2 + \log \left(1 + \sum_{i=1}^K \exp C_K(G(z))_i \right)$$

- Randomly sample input seed image x from training set.
- Each counterfactual image $G(z^*)$ is augmented to the training set with class label $K + 1$.

Experiments



- Open set detection

| Method | CIFAR-10 | SVHN | MNIST |
|-------------------|--------------------|--------------------|--------------------|
| Softmax Threshold | .677 ± .038 | .886 ± .014 | .978 ± .006 |
| OpenMax | .695 ± .044 | .894 ± .013 | .981 ± .005 |
| G-OpenMax* | .675 ± .044 | .896 ± .017 | .984 ± .005 |
| Ours | .699 ± .038 | .910 ± .010 | .988 ± .004 |

- Closed set accuracy

| Method | CIFAR-10 | SVHN | MNIST |
|-----------------|--------------------|--------------------|-------------|
| Softmax/OpenMax | .801 ± .032 | .947 ± .006 | .995 ± .002 |
| G-OpenMax* | .816 ± .035 | .948 ± .008 | .996 ± .001 |
| Ours | .821 ± .029 | .951 ± .006 | .996 ± .001 |



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Learning Placeholders for Open-Set Recognition

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CVPR 2021

Motivation

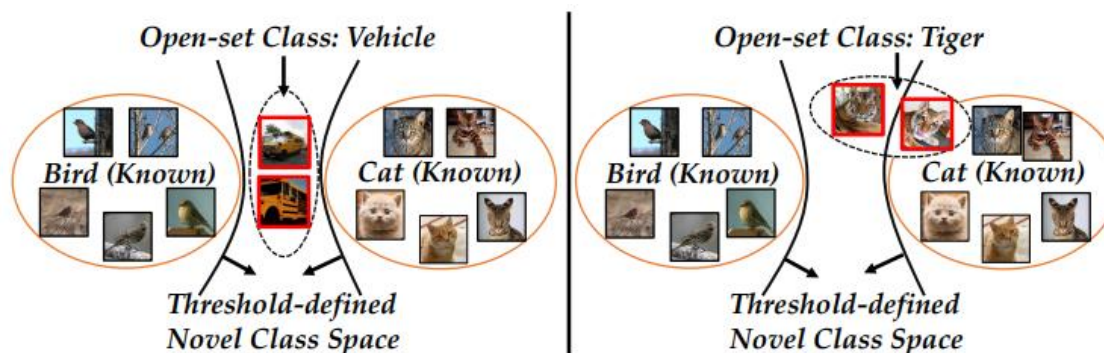


- Thresholding

$$y^* = \begin{cases} \arg \max_{y_i} P(y_i|x) & \text{if } \max_{y_i} P(y_i|x) > \delta \\ \text{unknown} & \text{else} \end{cases}$$

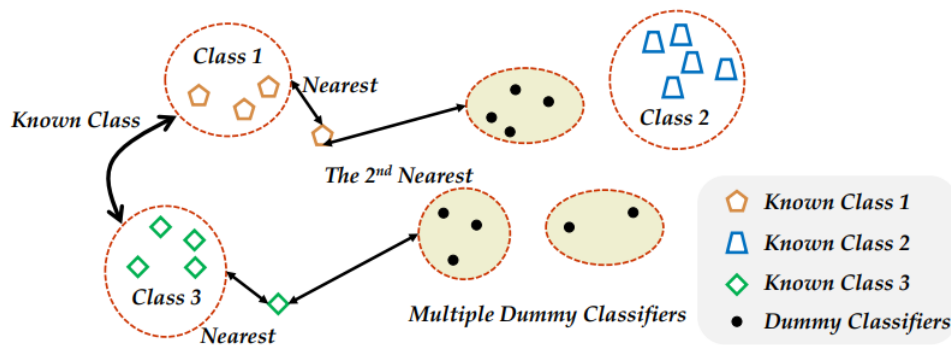
- Potential limitation

- It is difficult to find the optimal **global** threshold.
- DNNs can output incorrect high-confidence predictions when faced with test data from outside the training distribution.

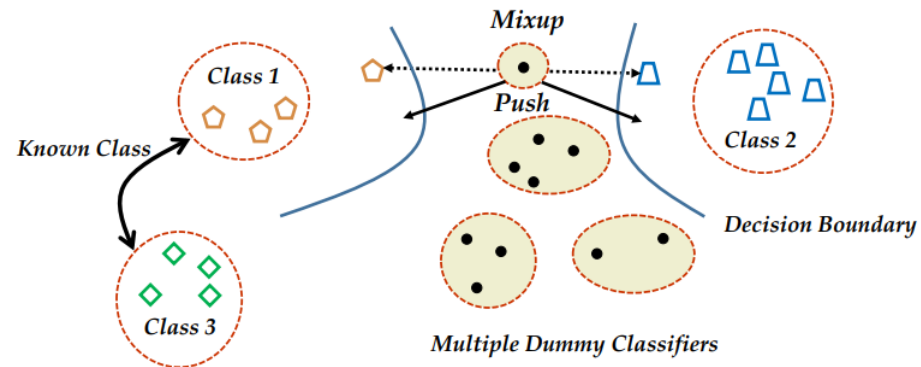


Learning placeholders for OS recognition

- Classifier placeholder
 - Augmenting the closed-set classifier with a **dummy classifier**, which adaptively outputs the **class-specific threshold** to separate known and unknown
- Data placeholder
 - Mimicking the emergence of novel classes, and transforming open-set training into closed-set training



(a) Learning classifier placeholders



(b) Learning data placeholders

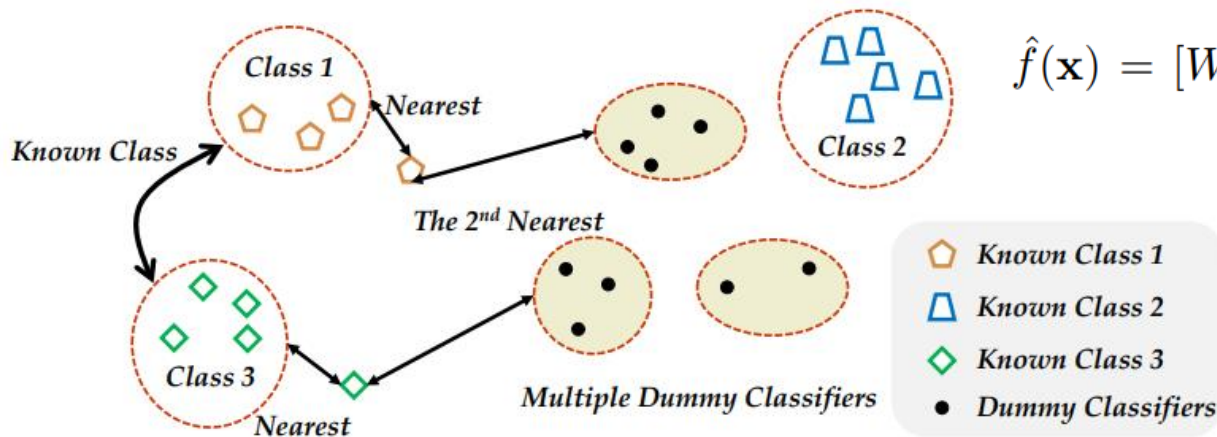
Learning placeholders for OS recognition

- Classifier placeholder

- A dummy classifier $\hat{f}(\mathbf{x}) = [W^\top \phi(\mathbf{x}), \hat{\mathbf{w}}^\top \phi(\mathbf{x})]$
- Making the dummy classifier to output the **second-largest** probability for known instances.

$$l_1 = \sum_{(\mathbf{x}, y) \in \mathcal{D}_{tr}} \ell(\hat{f}(\mathbf{x}), y) + \beta \ell(\hat{f}(\mathbf{x}) \setminus y, K + 1)$$

Removing the probability of ground truth label.



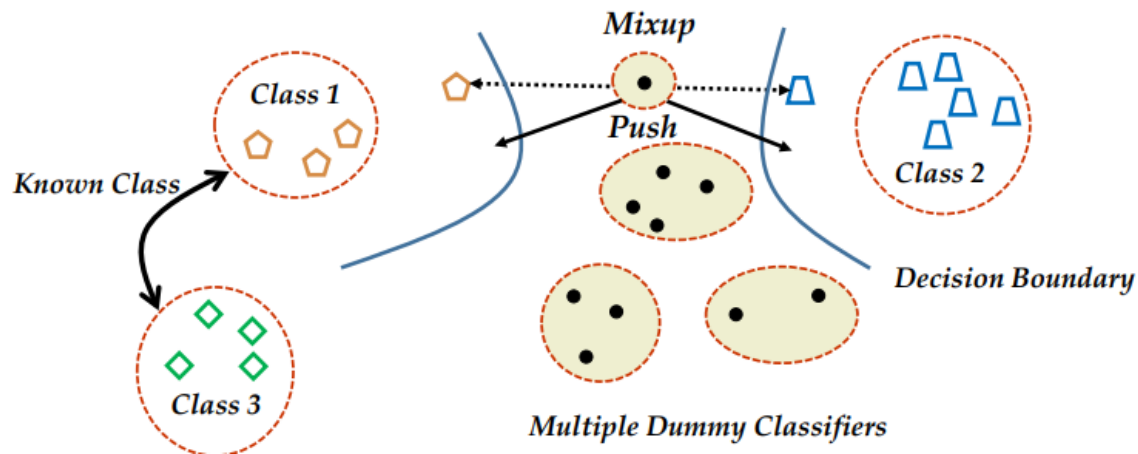
Learning placeholders for OS recognition

- Data placeholder

- The distribution of these instances seems novel, and the generating process should be quick.
- Manifold mixup

$$\tilde{\mathbf{x}}_{pre} = \lambda \phi_{pre}(\mathbf{x}_i) + (1 - \lambda) \phi_{pre}(\mathbf{x}_j), y_i \neq y_j$$

$$l_2 = \sum_{(\mathbf{x}_i, \mathbf{x}_j) \in \mathcal{D}_{tr}} \ell([W, \hat{\mathbf{w}}]^\top \phi_{post}(\tilde{\mathbf{x}}_{pre}), K + 1)$$



Experiments



- Open set detection

| Methods | SVHN | CIFAR10 | CIFAR+10 | CIFAR+50 | Tiny-ImageNet |
|---------------|-------------|-------------|-------------|-------------|---------------|
| Softmax | 88.6 | 67.7 | 81.6 | 80.5 | 57.7 |
| OpenMax [3] | 89.4 | 69.5 | 81.7 | 79.6 | 57.6 |
| G-OpenMax [6] | 89.6 | 67.5 | 82.7 | 81.9 | 58.0 |
| OSRCI [22] | 91.0 | 69.9 | 83.8 | 82.7 | 58.6 |
| C2AE [24] | 89.2 | 71.1 | 81.0 | 80.3 | 58.1 |
| GFROSR [26] | 93.5 | 83.1 | 91.5 | 91.3 | 64.7 |
| PROSER | 94.3 | 89.1 | 96.0 | 95.3 | 69.3 |

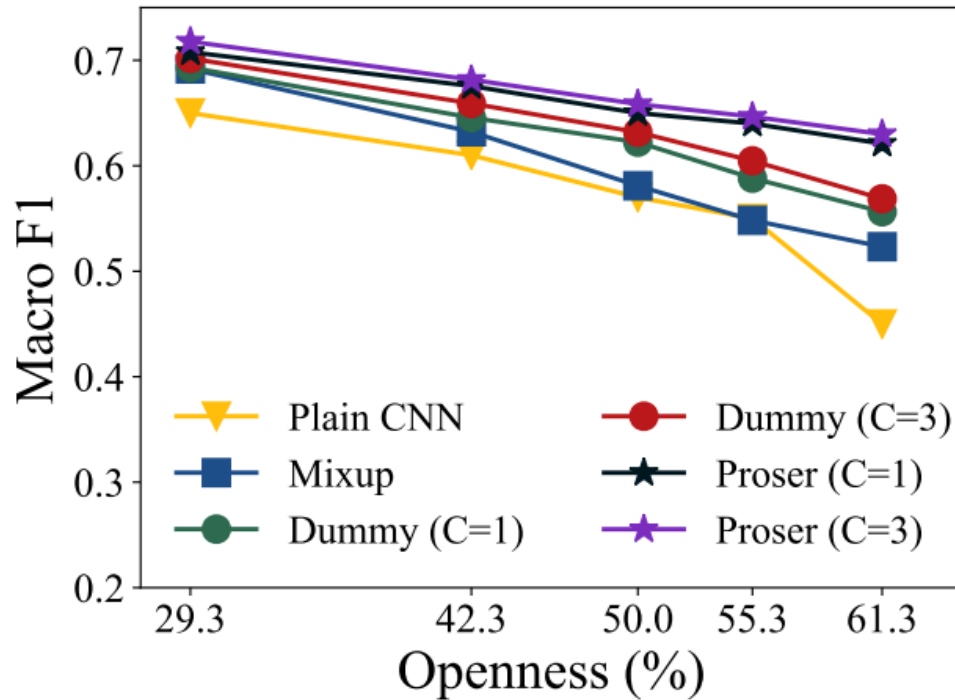
- Closed set accuracy

| Methods | SVHN | CIFAR10 | Tiny-ImageNet |
|---------------|-------------|-------------|---------------|
| Plain CNN | 96.5 | 92.8 | 52.2 |
| PROSER | 96.4 | 92.6 | 52.1 |

Experiments



- Ablation studies

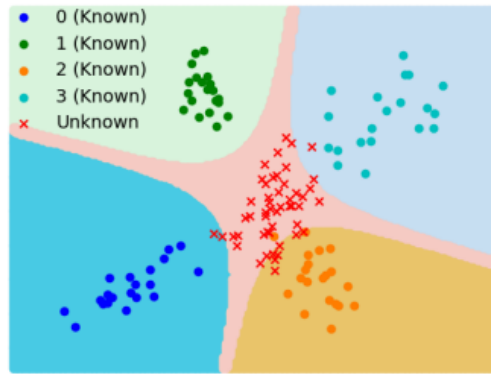


$$\text{Openness} = 1 - \sqrt{\frac{N_{train}}{N_{test}}}$$

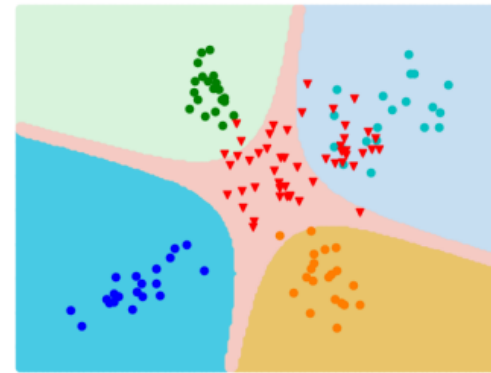
Experiments



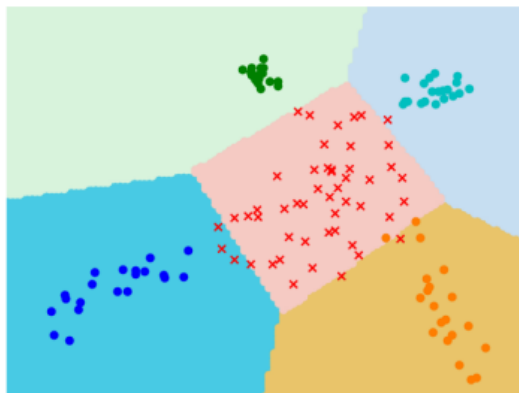
- Visualization of Decision Boundaries



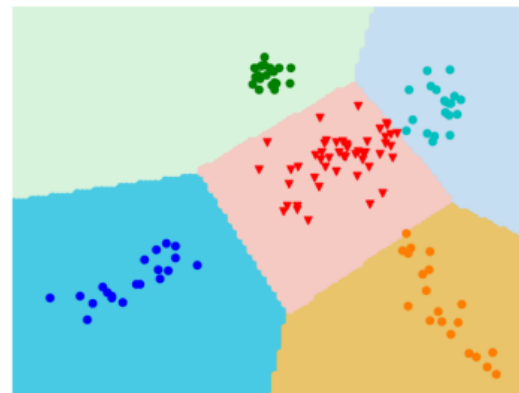
(a) Thresholding when Class 4 is novel



(b) Thresholding when Class 5 is novel



(c) PROSER when Class 4 is novel



(d) PROSER when Class 5 is novel



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THANKS
